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#!/usr/bin/python
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# Date : 2014-3-6
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#
# This is sample program of remote control Manson HCS series power supply under Raspberry Pi.
# The pySerial modulde is required to run this program. you can install by using
#
# sudo apt-get install python-serial
#
# Raspbian version : Kernel 3.10.30+
#
# USB driver : Kernel build-in cp210x driver.
#
# Testing model: HCS-3102, 1-36VDC Max 5A

import serial, time      # load serial communication and time control module

# Configure Port as baudrate 9600, Data 8bits, Parity None, 1 Stop bit. /dev/ttyUSB0 is virtual serial
port
ser = serial.Serial('/dev/ttyUSB0', 9600, timeout=0,
                    bytesize=serial.EIGHTBITS,
                    parity=serial.PARITY_NONE,
                    stopbits=serial.STOPBITS_ONE)

x=1 # set dummy variable

if ser.isOpen(): #exit if USB port is not open
    try:
        ser.flushInput() #flush input buffer, discarding all its contents
        ser.flushOutput() #flush output buffer, aborting current output

        #Set PSU OUTPUT off
        print("Set PSU OUTPUT off")
        while x:          # Loop to confirm PSU is received the command correctly.
            ser.write("SOUT1\r")      # Send SOUT1 to PSU. Each command must end with '\r'.
            time.sleep(0.5)           # Give serial port sometime to receive the command.
            response=ser.readline()   # Get reply from PSU
            if response == '':continue
            print(response)
            break
        time.sleep(3)

        #Set PSU output to 10V
        print("Set PSU OUTPUT to 10V")
        while x:
            ser.write("VOLT100\r")    # Send set voltage command. 100 means 10.0V
            time.sleep(0.5)
            response=ser.readline()
            if response == '':continue
            print(response)
            break
        time.sleep(3)

        #Get PSU setting
        print("Get PSU OUTPUT setting")
        while x:
            ser.write("GETS\r")       # Get setting information
            time.sleep(0.5)
            response=ser.readline()
            if response == '':continue

            voltage=response[:3] # PSU return string in format "100200", that means 10.0V, 2.00A,
            current=response[3:6] # then use first 3 data for voltage and next 3 data for current.
            print(voltage[:2]+'.'+voltage[2:]+ 'V')
            print(current[:1]+'.'+current[1:]+ 'A')
            break
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time.sleep(3)

#Set PSU OUTPUT on
print("Set PSU OUTPUT on")
while x:
    ser.write("SOUT0\r") # Set PSU output 0n
    time.sleep(0.5)
    response=ser.readline()
    if response == '':continue
    print(response)
    break
time.sleep(3)

#Set PSU output to 15V
print("Set PSU OUTPUT to 15V")
while x:
    ser.write("VOLT150\r") # change Votlage setting
    time.sleep(0.5)
    response=ser.readline()
    if response == '':continue
    print(response)
    break
time.sleep(3)

#Set PSU output to 2A
print("Set PSU OUTPUT to 2A")
while x:
    ser.write("CURR200\r") # change Current setting
    time.sleep(0.5)
    response=ser.readline()
    if response == '':continue
    print(response)
    break
time.sleep(3)

ser.close()

except Exception, e1:
    print "Error communicating...: " + str(e1)

else:
    print "Cannot open serial port "
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